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ISSN NO: 2454-7514
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# A SYSTEM OF SEMILINEAR ELLIPTIC NEUMANN BOUNDARY VALUE PROBLEM 

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Abstract: - In this paper we use the maximum principles to study symmetry properties of solutions for system of semilinear elliptic boundary value problem with Neumann condition, to the elliptic operators more general than the Laplacian operator on the unit ball in $n$ dimensional Euclidean space with $\boldsymbol{n} \geq 3$.

Keywords: Maximum principle; Radial symmetry; System of nonlinear elliptic

Boundary value problem, Neumann boundary condition.

AMS 2010: 34B15, 34B18, 35B06, 35B50.

## 1. INTRODUCTION

To study the behavior of solutions of system of elliptic boundary value problems with Neumann boundary conditions is an interesting problem in the point of view of differential geometry and elliptic boundary value problems. The problem of the interest is

$$
\begin{gathered}
\int \mathrm{u}=\mathrm{f}_{1}(\mathrm{v}) ; \quad \text { in } \mathrm{B} \\
\int \mathrm{v}=\mathrm{f}_{2}(\mathrm{u}) \quad \text { in } \mathrm{B} \\
\partial \mathrm{u} / \partial \eta=\mathrm{g}_{1}(\mathrm{v}) \text { on } \partial \mathrm{B}
\end{gathered}
$$

$$
\partial \mathrm{v} / \partial \eta=\mathrm{g}_{2}(\mathrm{u}) \text { on } \partial \mathrm{B} .
$$

Where B is ball of unit radius in $\mathrm{R}^{\mathrm{n}}$,
$\partial / \partial \boldsymbol{\eta}$ denote the outer normal derivative to $\partial \mathrm{B}$ and $\mathrm{f}_{1} ; \mathrm{f}_{2} ; \mathrm{g}_{1}$ and $\mathrm{g}_{2}$ are functions defined in $\mathbf{R}$.

The maximum principle is one of the most used tools in the study of some elliptic boundary value problems. A version of maximum principle allows us to compare locally surfaces that coincide at a point. Also the maximum principle and Alexandrov reflection principle have been used to prove symmetry of solutions of boundary value problems with respect to some point, some plane, and symmetry of domains by the authors

Serrin [14], Gidas, Ni and Nirenberg [4, 5], Berestycki and Nirenberg [2]. Castro, Maya and Shivaji [3] summarized the recent developments of semipositone problems.

Reichel [13] obtained the radial symmetry for the domain and solutions of

$$
\int \mathrm{u}+\mathrm{f}(\mathrm{u} ;|\nabla \mathrm{u}|)=0
$$

on exterior domain subject to the over determined boundary conditions

$$
\partial u / \partial v=\text { const } ; \quad u>0
$$

on the boundary, by using Alexandro_-Serrin method of moving hyperplanes. Bensedik and Bouchekif [1] proved the symmetry result of positive solutions for a Neumann boundary value problem,

$$
\begin{aligned}
\mathrm{L}(\mathrm{u})=-\mathrm{u}^{\prime \prime}+\mathrm{q}^{2} \mathrm{u} & =|\mathrm{u}|^{\mathrm{p}} \mathrm{f}(\mathrm{x}) ; \mathrm{x} \varepsilon(\mathrm{a} ; \mathrm{b}) \\
\mathrm{u}^{\prime}(\mathrm{a}) & =\mathrm{u}^{\prime}(\mathrm{b})
\end{aligned}
$$

making generalization of the work of Padro J. Toress, [15]. In 2012, Marin, Ortiz and Rodriguez [ 9,10 ] proved the symmetry of Neumann boundary value problem.

In this paper we prove that solution of the system of elliptic boundary value problem with Neumann condition,

$$
\begin{gathered}
a\left(\mathrm{u}+\mathrm{b} \Sigma^{\mathrm{n}}{ }_{\mathrm{i}=1} \quad \mathrm{u}_{\mathrm{i}}=\mathrm{f}_{1}(\mathrm{v})\right. \\
\mathrm{a}\left(\mathrm{v}+\mathrm{b} \Sigma^{\mathrm{n}}{ }_{\mathrm{i}=1} \quad \mathrm{v}_{\mathrm{i}}=\mathrm{f}_{2}(\mathrm{u})\right. \\
\partial \mathrm{u} / \partial \eta=\mathrm{g}_{1}(\mathrm{v}) \\
\partial \mathrm{v} / \partial \eta=\mathrm{g}_{2}(\mathrm{u})
\end{gathered}
$$

are radially symmetric with respect to the origin, where $\mathrm{a}: \mathbf{B} \rightarrow \mathrm{R}$ is a bounded function and symmetric with respect to the origin such that $\mathrm{a}(\mathrm{x})>$ 0 for all $\mathrm{x} \varepsilon \mathbf{B}$ and $\mathrm{b}: \mathbf{B} \rightarrow \mathrm{R}$ is a bounded and odd function. Let $\eta$ denote the normal vector to $\partial \mathrm{B}$ and $\mathrm{f}_{1} ; \mathrm{f}_{2} ; \mathrm{g}_{1}$ and $\mathrm{g}_{2} \varepsilon \mathrm{C}(\mathbf{R})$. Furthermore suppose that $\mathrm{f}_{1} ; \mathrm{f}_{2}$ are strictly increasing and $\mathrm{g}_{1}, \mathrm{~g}_{2}$ are strictly decreasing.

Our proof shows that the techniques used in $[2,4,7$, 14] for study of symmetric solutions of the ellipotic boundary value problem with Dirichlet condition can be applied to prove symmetry of solutions of the ellipotic boundary value problem with Neumann condition. Recently author Patil [6] proved the symmetry result for the Neumann boundary value problem, $-u "+q^{2} u=u^{2} x^{2}$ with boundary condition $u^{\prime}(-1)=u^{\prime}(1)$ in the interval $(-1,1)$.

## 2. MAIN RESULT

Now we state the main theorem for symmetry of solutions of system of elliptic Neumann boundary value problem.

## THEOREM 2.1

Let $(\mathbf{u}, \mathbf{v}) \varepsilon C^{2}(B) \cup C^{0}(B)$ be a positive solution of the elliptic boundary value problem with Neumann condition.

$$
\begin{gathered}
a \int u+b i \Sigma^{n}{ }_{i=1} u_{i}=f_{1}(v) \\
a \int_{v}+b \Sigma^{n}{ }_{i=1} v_{i}=f_{2}(u) \\
\partial u / \partial \eta=g_{1}(v) \\
\partial v / \partial \eta=g_{2}(u)
\end{gathered}
$$

Where $\mathrm{a}, \mathrm{b}, \mathrm{f}_{1} ; \mathrm{f}_{2} ; \mathrm{g}_{1}$ and $\mathrm{g}_{2}$ are as defined in previous section. Then the solution ( $u$; v) must be radially symmetric with respect to the origin.

Proof: Let $\mathrm{x} \varepsilon \mathbf{B}$ and $\mathrm{x}^{0}$ denotes the reflection of x with respect to the hyperplane $x_{n}=0$.

Then x and x ' both are in B.
$\therefore$ System of equations in 2.1 is satisfied by both x and $x$ '.

$$
\begin{gather*}
a\left(\mathrm{u}(\mathrm{x})+\mathrm{b} \sum^{\mathrm{n}}{ }_{\mathrm{i}=1} \mathrm{u}_{\mathrm{i}}(\mathrm{x})=\mathrm{f}_{1}(\mathrm{v}(\mathrm{x})) \text { in } \mathrm{B}\right.  \tag{2.2}\\
\mathrm{a}\left(\mathrm{v}(\mathrm{x})+\mathrm{b} \sum^{\mathrm{n}}{ }_{\mathrm{i}=1} \mathrm{v}_{\mathrm{i}}(\mathrm{x})=\mathrm{f}_{2}(\mathrm{u}(\mathrm{x})) \text { in } \mathrm{B}\right.  \tag{2.2}\\
\partial \mathrm{u}(\mathrm{x}) / \partial \boldsymbol{\eta}=\mathrm{g}_{1}(\mathrm{v}(\mathrm{x})) \text { on } \partial \mathrm{B}  \tag{2.3}\\
\partial \mathrm{v}(\mathrm{x}) / \partial \boldsymbol{\eta}=\mathrm{g}_{2}(\mathrm{u}(\mathrm{x})) \text { on } \partial \mathrm{B} \tag{2.4}
\end{gather*}
$$

$x^{\prime}$ also satisfies the same equations that $x$ does.
$\mathrm{a}\left(\mathrm{u}\left(\mathrm{x}^{\prime}\right)+\mathrm{b} \sum^{\mathrm{n}} \mathrm{i}=1^{\mathrm{u}_{\mathrm{i}}}\left(\mathrm{x}^{\prime}\right)=\mathrm{f}_{1}\left(\mathrm{v}\left(\mathrm{x}^{\prime}\right)\right)\right.$ in $B$
$a\left(v\left(x^{\prime}\right)+b \Sigma^{n}{ }_{i=1} v_{i}\left(x^{\prime}\right)=f_{2}\left(u\left(x^{\prime}\right)\right) \quad\right.$ in $B$
$\partial \mathrm{u}\left(\mathrm{x}^{\prime}\right) / \partial \boldsymbol{\eta}=\mathrm{g}_{1}\left(\mathrm{v}\left(\mathrm{x}^{\prime}\right)\right) \quad$ on $\partial \mathrm{B} \quad$ (2.8)
$\partial \mathrm{v}\left(\mathrm{x}^{\prime}\right) / \partial \boldsymbol{\eta}=\mathrm{g}_{2}\left(\mathrm{u}\left(\mathrm{x}^{\prime}\right)\right) \quad$ on $\partial \mathrm{B}$
We define the function $\mathrm{w}_{1}$ and $\mathrm{w}_{2}$ as follows,

$$
\begin{align*}
& \mathrm{w}_{1}=\mathrm{u}(\mathrm{x})-\mathrm{u}\left(\mathrm{x}^{\prime}\right)  \tag{2.10}\\
& \mathrm{w}_{2}=\mathrm{v}(\mathrm{x})-\mathrm{v}\left(\mathrm{x}^{\prime}\right) \tag{2.11}
\end{align*}
$$

In consequence $W_{1}$ and $w_{2}$ satisfies
$\mathrm{a} \int \mathrm{w}_{1}(\mathrm{x})+\mathrm{b} \Sigma^{\mathrm{n}}{ }_{\mathrm{i}=1} \quad \mathrm{w}_{1 \mathrm{i}}(\mathrm{x})=\mathrm{f}_{1}(\mathrm{v}(\mathrm{x}))-\mathrm{f}_{1}\left(\mathrm{v}\left(\mathrm{x}^{\prime}\right)\right)$ in B (2.12)
$\mathrm{a}\left(\mathrm{w}_{2}(\mathrm{x})+\mathrm{b} \sum^{\mathrm{n}}{ }_{\mathrm{i}=1} \quad \mathrm{w}_{2 \mathrm{i}}(\mathrm{x})=\mathrm{f}_{2}(\mathrm{v}(\mathrm{x}))-\mathrm{f}_{2}\left(\mathrm{v}\left(\mathrm{x}^{\prime}\right)\right)\right.$ in B
$\partial \mathrm{w}_{1}(\mathrm{x}) / \partial \boldsymbol{\eta}=\mathrm{g}_{1}(\mathrm{v}(\mathrm{x}))-\mathrm{g}_{1}\left(\mathrm{v}\left(\mathrm{x}^{\prime}\right)\right)$ on $\partial \mathrm{B}$
$\partial \mathrm{w}_{2}(\mathrm{x}) / \partial \boldsymbol{\eta}=\mathrm{g}_{2}(\mathrm{u}(\mathrm{x}))-\mathrm{g}_{2}\left(\mathrm{u}\left(\mathrm{x}^{\prime}\right)\right)$ on $\partial \mathrm{B}$
$\mathrm{w}_{1}=0, \mathrm{w}_{1}=0$ in $\mathbf{B} \cup\left\{\mathrm{x}_{\mathrm{n}}=0\right\}$
Since $w_{1}$ and $w_{2}$ are continuous in $\mathbf{B}$, there exist points $x_{m}$ and $x_{M}$ such that

$$
\begin{aligned}
& \mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{m}}\right)=\min _{\mathbf{B}}\left(\mathbf{w}_{\mathbf{1}}\right) \\
& \mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{M}}\right)=\max _{\mathbf{B}}\left(\mathbf{w}_{\mathbf{1}}\right) \\
& \mathrm{w}_{2}\left(\mathrm{x}_{\mathrm{m}}\right)=\min _{\mathbf{B}}\left(\mathbf{w}_{\mathbf{2}}\right)
\end{aligned}
$$

$$
\mathrm{w}_{2}\left(\mathrm{x}_{\mathrm{M}}\right)=\max _{\mathbf{B}}\left(\mathbf{w}_{\mathbf{2}}\right)
$$

We claim that the points $x_{m}$ and $x_{M}$, cannot be in $\partial \mathrm{B}$.

Suppose $\mathrm{x}_{\mathrm{M}} \varepsilon \partial \mathrm{B}$ and satisfies
$\mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{M}}\right)>\mathrm{w}_{1}(\mathrm{x}), \mathrm{w}_{2}\left(\mathrm{x}_{\mathrm{M}}\right)>\mathrm{w}_{2}(\mathrm{x})$ for all $\mathrm{x} \varepsilon B$.
Therefore

$$
\begin{array}{ll}
\partial \mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{M}}\right) / \partial \eta & >0 \\
\partial \mathrm{w}_{2}\left(\mathrm{x}_{\mathrm{M}}\right) / \partial \eta & >0
\end{array}
$$

And

$$
\begin{array}{ll}
\mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{M}}\right) & >0 \\
\mathrm{w}_{2}\left(\mathrm{x}_{\mathrm{M}}\right) & >0
\end{array}
$$

In consequence

$$
\begin{aligned}
& \mathrm{g}_{2}\left(\mathrm{u}\left(\mathrm{x}_{\mathrm{M}}\right)\right)-\mathrm{g}_{2}\left(\mathrm{u}\left(\mathrm{x}^{\prime}{ }_{\mathrm{M}}\right)\right) \rho 0 \\
& \mathrm{~g}_{1}\left(\mathrm{v}\left(\mathrm{x}_{\mathrm{M}}\right)\right)-\mathrm{g}_{1}\left(\mathrm{v}\left(\mathrm{x}^{\prime}{ }_{\mathrm{M}}\right)\right) \rho 0
\end{aligned}
$$

Since $g_{1}$ and $g_{2}$ are strictly decreasing, we have,
$\mathrm{u}\left(\mathrm{x}_{\mathrm{M}}\right) \beta \mathrm{u}\left(\mathrm{x}^{\prime}{ }_{\mathrm{M}}\right)$ and $\mathrm{v}\left(\mathrm{x}_{\mathrm{M}}\right) \beta \mathrm{v}\left(\mathrm{x}^{\prime}{ }_{\mathrm{M}}\right)$
Then $\mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{M}}\right) \beta 0$ and $\mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{M}}\right) \beta 0$
Which contradicts to $\mathrm{w} 1\left(\mathrm{x}_{\mathrm{M}}\right)>0$ and $\mathrm{w}_{2}\left(\mathrm{x}_{\mathrm{M}}\right)>0$
.Thus, $\mathrm{x}_{\mathrm{M}}$ cannot be in $\partial \mathrm{B}$.
Suppose $x_{m} \varepsilon \partial B$ and satisfies
$\mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{m}}\right)<\mathrm{w}_{1}(\mathrm{x}), \mathrm{w}_{2}\left(\mathrm{x}_{\mathrm{m}}\right)<\mathrm{w}_{2}(\mathrm{x})$ for all $\mathrm{x} \varepsilon \mathrm{B}$
Therefore,

$$
\begin{array}{ll}
\partial w_{1}\left(x_{m}\right) / \partial \eta & <0 \\
\partial w_{2}\left(x_{m}\right) / \partial \eta & <0
\end{array}
$$

And

$$
\begin{array}{ll}
\mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{m}}\right) & <0 \\
\mathrm{w}_{2}\left(\mathrm{x}_{\mathrm{m}}\right) & <0
\end{array}
$$

In consequence

$$
\begin{aligned}
& \mathrm{g}_{2}\left(\mathrm{u}\left(\mathrm{x}_{\mathrm{m})}\right)-\mathrm{g}_{2}\left(\mathrm{u}\left(\mathrm{x}_{\mathrm{m}}^{\prime}\right)\right) \beta 0\right. \\
& \mathrm{g}_{1}\left(\mathrm{v}\left(\mathrm{x}_{\mathrm{m}}\right)\right)-\mathrm{g}_{1}\left(\mathrm{v}\left(\mathrm{x}_{\mathrm{m}}^{\prime}\right)\right) \beta 0
\end{aligned}
$$

Since $g_{1}$ and $g_{2}$ are strictly decreasing, we have,
$u\left(x_{m}\right) \rho u\left(x^{\prime}{ }_{m}\right)$ and $v\left(x_{m}\right) \rho v\left(x^{\prime}{ }_{m}\right)$
Then $\mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{m}}\right) \rho 0$ and $\mathrm{w} 1\left(\mathrm{x}_{\mathrm{m}}\right) \rho 0$
Which contradicts to $\mathrm{w} 1\left(\mathrm{x}_{\mathrm{m}}\right)<0$ and $\mathrm{w}_{2}\left(\mathrm{x}_{\mathrm{m}}\right)<0$
.Thus, $\mathrm{x}_{\mathrm{m}}$ cannot be in $\partial \mathrm{B}$.
Hence $\mathrm{x}_{\mathrm{M}}, \mathrm{x}_{\mathrm{m}} \varepsilon \mathrm{B}$.
So,

$$
\begin{aligned}
& \mathrm{a}\left(\mathrm{x}_{\mathrm{m}}\right) \int \mathrm{w}_{1} \mathrm{x}_{\mathrm{m}}+\mathrm{b}\left(\mathrm{x}_{\mathrm{m}}\right) \sum_{\mathrm{i}=1}{ }^{\mathrm{n}} \mathrm{w}_{1 \mathrm{i}}\left(\mathrm{x}_{\mathrm{m}}\right) \rho 0 \\
& \mathrm{a}\left(\mathrm{x}_{\mathrm{m}}\right) \int \mathrm{w}_{2} \mathrm{x}_{\mathrm{m}}+\mathrm{b}\left(\mathrm{x}_{\mathrm{m}}\right) \sum_{\mathrm{i}=1}^{\mathrm{n}} \mathrm{w}_{2 \mathrm{i}}\left(\mathrm{x}_{\mathrm{m}}\right) \rho 0 \\
& \mathrm{a}\left(\mathrm{x}_{\mathrm{M}}\right) \int \mathrm{w}_{1} \mathrm{x}_{\mathrm{M}}+\mathrm{b}\left(\mathrm{x}_{\mathrm{M}}\right) \sum_{\mathrm{i}=1}^{\mathrm{n}} \mathrm{w}_{1 \mathrm{i}}\left(\mathrm{x}_{\mathrm{M}}\right) \beta 0 \\
& \mathrm{a}\left(\mathrm{x}_{\mathrm{M}}\right) \int \mathrm{w}_{2} \mathrm{x}_{\mathrm{M}}+\mathrm{b}\left(\mathrm{x}_{\mathrm{M}}\right) \sum_{\mathrm{i}=1}{ }^{\mathrm{n}} \mathrm{w}_{2 \mathrm{i}}\left(\mathrm{x}_{\mathrm{M}}\right) \beta 0
\end{aligned}
$$

Since $f_{1}$ and $f_{2}$ are strictly increasing we conclude that,

$$
\begin{aligned}
& \mathrm{u}\left(\mathrm{x}_{\mathrm{m}}\right) \rho \mathrm{u}\left(\mathrm{x}^{\prime}{ }_{\mathrm{m}}\right) \\
& \mathrm{u}\left(\mathrm{x}_{\mathrm{M}}\right) \beta \mathrm{u}\left(\mathrm{x}^{\prime}{ }_{\mathrm{M}}\right) \\
& \mathrm{v}\left(\mathrm{x}_{\mathrm{m}}\right) \rho \mathrm{v}\left(\mathrm{x}^{\prime}{ }_{\mathrm{m}}\right) \\
& \mathrm{v}\left(\mathrm{x}_{\mathrm{M}}\right) \rho \mathrm{v}\left(\mathrm{x}^{\prime}{ }_{\mathrm{M}}\right)
\end{aligned}
$$

Then

$$
\begin{gathered}
\mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{m}}\right)=\mathrm{w}_{1}\left(\mathrm{x}_{\mathrm{M}}\right)=0 \text { and } \\
\mathrm{w}_{2}\left(\mathrm{x}_{\mathrm{m}}\right)=\mathrm{w}_{2}\left(\mathrm{x}_{\mathrm{M}}\right)=0
\end{gathered}
$$

Hence, $w_{1}=0$; $w 2=0$ in $\mathbf{B}$, So ( $u, v$ ) is symmetric with respect to the plane $\mathrm{x}_{\mathrm{n}}=0$.

Since B is unit ball and we can apply the same arguments in all directions, it follows that $u$ is radially symmetric with respect to the origin.

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